## DATA ACQUISITION BOARDS

## SSI 1276-INTERFACE - BOARD

## HIGHLIGHTS

# - INTERFACES 4 SSI-ENCODER <br> - ZERO POSITION SELECTABLE <br> - ALL INPUTS OPTICALLY ISOLATED - 6 DIGITAL OUTPUTS <br> - ALL OUTPUTS OPTICALLY ISOLATED 

## General

The SSI 1276 board represents an input/output board for IBM compatible computers. It is especially designed for data transfer from absolute encoders with a SSI interface to a host computer.
The SSI 1276 board is supplied with 4 independent SSI interfaces. All inputs are optically isolated from PC ground. Therefore the board will work well under heavy industrial environment.
Beside the SSI interfaces there are 6 optoisolated digital outputs for switching and or controlling of external components.

## Encoder inputs

It is possible to connect 4 encoder to the 4 inputs of the SSI-Interface board.
Each input may be programmed independently of each other concerning clock frequency and length of received datas. This is done by programming an counter circuit of the type 82C54.
If a data transfer from the encoder to the computer is completed an interrupt is generated.
Each encoder input is supplied with an additional digital input. This input is a "Zero Input". An input signal (low voltage) at the "Zero Input" defines the zero position of the encoder. Zeroing is accompanied by an interrupt.

## Digital outputs

The digital outputs are isolated by optocouplers. not only from the computer ground but also from each other. The outputs, open collctor outputs, may switch up to 30 V and 25 mA .

## Installation

Refer to the switches and jumpers information of this chapter

1. Select the I/O adress by setting the 7-pole DIPswich "S1"
2. Select the interrupt channel by the jumper J1..J4. It must be noted, the interrupts are for AT and not for XT compatible buses!
3. Power OFF all devices (display, printer,...ect.) attached to your computer then power OFF your computer system.
4. Disconnect all cables from the rear of your computer.
5. Remove the system unit cover and the expansion slot cover from the slot you wish to use.
6. Hold the adapter by its top corners and press it down into the expansion slot. Make sure that the adapter is fully seated in the expansion slot, then secure the adapter with the screw you removed in step 6.
7. Replace the computer chassis cover and reconnect all cables to the rear of the computer. Power ON the computer

## I/O address selection

The base address can be selected by the DIPswitch "S1". The I/O base adress can be set within the address range from 100 H to 3FFH (factory setting $=300 \mathrm{H}$ )
If you need to adjust it to some other address ranges, the switch settings are illustrated as below:
DIP-switch is numbered 1...7. Switch position ON is selected as " 0 ".

$$
\begin{aligned}
& 7=200 \mathrm{H} \\
& 6=100 \mathrm{H} \\
& 5=80 \mathrm{H} \\
& 4=40 \mathrm{H} \\
& 3=20 \mathrm{H} \\
& 2=10 \mathrm{H} \\
& 1=8 \mathrm{H}
\end{aligned}
$$

## Interrupt channel selection

The interrupt channel can be configured by J1...J4. Selectable interrupts are IRQ10, IRQ11, IRQ12, and IRQ15. Factory setting is IRQ12 (J2)

$$
\begin{aligned}
& \mathrm{J} 1=\mathrm{IRQ15} \\
& \mathrm{~J} 2=\text { IRQ12 } 2 \\
& \mathrm{~J} 3=\text { IRQ11 } \\
& \mathrm{J} 4=\text { IRQ10 } \\
& \text { Jumper } \mathrm{J} \text { is not used }
\end{aligned}
$$

## DATA ACQUISITION BOARDS

## Programming

The SSI 1276 board uses the I/O address range from base address +0 to base address +7 . The address function are illustrated as below:

| Port | Default | Direction | Function |
| :---: | :---: | :---: | :---: |
| Base+0 | 300 H | read/write | Counter 0 |
| Base+1 | 301 H | read/write | Counter 1 |
| Base+2 | 302 H | read/write | Counter 2 |
| Base+3 | 303 H | read/write | Control Word |
| Base+4 | 304 H | read | Data Bits 0...7 |
| Base+5 | 305 H | read | Data Bits 8...15 |
| Base+6 | 306 H | read | Data Bits 16...24 |
| Base+7 | 307 H | read | Bit $0=$ Data Bit 25 <br> Bit 1 $\ldots .4=$ Zero Bit |
|  |  | write | Bit $0 / 1=$ Input Address <br> Bit 2..7 $=$ digital Outputs |

## Counter device 82C54

The 82C54 contains 3 identical, independent counter blocks. Each counter provides the same functions, but can be programmed to operate in different modes relative to each other (for full information see leaflet of the manufacturer).
The counter is a 16 -bit presettable synchronous down counter. Output latches provide a mechanism whereby the CPU can read the current contents of the counter.
Read and write of the counter content is done by the address base +0 , base +1 , and base +2 .
Different modes are programmed by writing a specific control word (address base +3 ). There are 6 different modes (mode 0 to mode 5). For programming the SSI1276 board the only the modes $0,1,2$, and 3 are used.
Address base +4 , base +5 , base +6 and the LSB of base +7 are datas (max. 25 bit) received from the encoder. When reading address base+7, Bit 1 to 4 are indicating zeroing the encoders 1 to4.
When writing address base +7 , bit 0 and 1 are addressing the encoder (binary code) of wich datas will be red. Bit 2 to 7 are the six digital outputs.

Control Word Format

| Control Word | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Function | SC1 | SC0 | RW1 | RW0 | M2 | M1 | M0 | BCD |


| Counter Selection |  |  |
| :---: | :---: | :---: |
| SC1 | SCO | Counter |
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 2 |


| Read/Write-Modes |  |  |
| :---: | :---: | :---: |
| RW1 | RWO | Function |
| 0 | 0 | Counter Latching |
| 0 | 1 | LSB |
| 1 | 0 | MSB |
| 1 | 1 | LSB / MSB |


| Modes 0 bis 5 |  |  |  |
| :---: | :---: | :---: | :---: |
| M2 | M1 | M0 | Function |
| 0 | 0 | 0 | Counter |
| 0 | 0 | 1 | mon. ext. Trigger |
| 0 | 1 | 0 | Frequency Divider |
| 0 | 1 | 1 | Frequency Divider |
| 1 | 0 | 0 | Impuls-soft. Trigger |
| 1 | 0 | 1 | Impuls-hard. Trigger |
|  |  |  |  |
| BCD |  |  |  |
| 0 |  |  | Function |
|  |  |  |  |

## Counter 0

Output frequency of counter 0 will be the clock frequency for the encoder. Therefore counter 0 must be programmed as divide-by-N counter (mode 3). By this mode internal clock frequency of 2 MHz is divided by value $N$.
Mode 3 is defined by the Control Word. The Control Word is written to address base+3. Subsequently counter 0 will be written with the binary value N (see examples 1 and 2 ).

## Counter 1

Counter 1 is used for counting the number of bits of the encoder (see datas of the used encoders). Input frequency of counter 1 is the output frequency of counter 0 . If only one encoder will be used, counter 1 will run in mode1 else in mode 0 .

## Counter 2

Counter 2 will be programmed in mode 2 and is used for installing the desired measuring rate. Input frequency of counter 2 is the output frequency of counter 0 . Counter 2 will work as divide by N counter. Attention must be paid, that the min. pause between two measurements will not be failed.
If counter 2 is not used it must be initialized too.

## DATA ACQUISITION BOARDS

## 1. Example 1

- Datas of the encoder 1
- Clock frequency $=100 \mathrm{kHz}$
- Resolution/turn = 4096
- Number of turns $=4096$
- Overall resolution $=24$ bit
- Data format: Multiturn

Adjusting clock freqency of the encoder 1 Internal Clock $=2 \mathrm{MHz}$
Encoder clock frequency $=100 \mathrm{kHz}$
Divider N for counter 0 :

$$
\mathrm{N}=2 \mathrm{MHz} / 0.1 \mathrm{MHz}=20(=14 \mathrm{H})
$$

## Programming of counter 1

Counter 1 must be programmed with

$$
25+1=26(=1 \mathbf{A H})
$$

Programming of 82C54
Control-Word Counter 0:


## Counter 0 :



## Counter 1:



Control-Word Counter 2:


## 2. Example 2

- Datas of the encoder 2
- Clock frequency $=200 \mathrm{kHz}$
- Resolution/turn $=4096$
- Number of turns = 1
- Overall resolution = 12 bit
- Data format: Singleturn

Adjusting clock freqency of the encoder 2
Internal Clock $=2 \mathrm{MHz}$
Encoder clock frequency $=200 \mathrm{kHz}$
Divider N for counter $\mathbf{0}$ :

$$
\mathrm{N}=2 \mathrm{MHz} / 0.2 \mathrm{MHz}=10(=\mathbf{0 A H})
$$

## Programming of counter 1

Counter 1 must be programmed with

$$
13+1=14 \text { (= 0EH) }
$$

## Programming of counter 2

Desired measuring rate $=100 \mathrm{~ms}$ $100 \mathrm{~ms} /(1 / 200 \mathrm{kHz})=20000(=4 \mathrm{E} 20 \mathrm{H})$

Programming of 82C54
Control-Word Counter 0:

| SC1 | SC0 | RW1 | RW0 | M2 | M1 | M0 | BCD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | $x$ | 1 | 1 | 0 |

Counter 0:

| 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Control-Word Counter 1:

| SC1 | SC0 | RW1 | RWO | M2 | M1 | M0 | BCD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |

Counter 1:


Control-Word Counter 2:

| SC1 | SCO | RW1 | RWO | M2 | M1 | MO | BCD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | 1 | 1 | $x$ | 1 | 0 | 0 |

Counter 2, LSB:


Counter 2, MSB:


## DATA ACQUISITION BOARDS

## Connector List

Encoder 1
Clock +
Pin 31
Clock -
Pin 32
Data +
Pin 37
Data -
Pin 19

## Encoder 2

Clock +
Clock -
Data +
Data -

## Encoder 3

Clock +
Pin 29
Clock -
Data +
Data -

## Encoder 4

Clock +
Pin 27
Clock -
Data +

Pin 28
Pin 22

Data -

Zero Inputs
Zero $1 \quad$ Pin 4
Zero $2 \quad$ Pin 3
Zero 3 Pin 1
Zero 4 Pin 2
GND Pin 20

Digital Outputs
Out 1 (Emitter) Pin 9
Out 1 (Collector) Pin 10
Out 2 (Emitter) Pin 5
Out 2 (Collector) Pin 6
Out 3 (Emitter) Pin 8
Out 3 (Collector) Pin 7
Out 4 (Emitter) Pin 12
Out 4 (Collector) Pin 11
Out 5 (Emitter) Pin 13
Out 5 (Collector) Pin 14
Out 6 (Emitter) Pin 16
Out 6 (Collector) Pin 15

Pin 21

## Technical Datas

In/Outputs

| Digital Outputs Voltage | $<60 \mathrm{VDC}$ |
| :--- | :--- |
| Digital Outputs Current | $<50 \mathrm{~mA}$ |
| Digital Outputs Power | $<150 \mathrm{~mW}$ |
| Clock Output | EIA RS 422 |
| Data Input | EIA RS 422 |


| ISA BUS | 5 VDC |
| :--- | :--- |
| Supply Voltage | 0.5 A |
| Current Consumption | $190{ }^{*} 108 \mathrm{~mm}$ |
| Dimensions | 220 g |
| Weight |  |



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